# **Course Syllabus**

### EE675 - Data analysis and control techniques for neurotechnology design

Ming Hsieh Department of Electrical and Computer Engineering University of Southern California

#### Instructor

Maryam M. Shanechi Email: shanechi@usc.edu Office Hours: TBA

Lectures: Tuesday and Thursday, 9:00am-10:50am, ZHS352

Units: 4

### **Course Description:**

This course teaches the data analysis, machine learning and control-theoretic tools used to study largescale datasets and systems, with emphasis on neural datasets and brain-machine interface systems. Topics include state-space modeling, dynamical systems, theory of point processes, Bayesian inference, expectation-maximization (EM), and optimal control. Applications include construction of neural encoding models, system-identification in neural systems, decoding neural data, analyzing neural receptive field plasticity, algorithms for brain-machine interfaces, and closed-loop neurostimulation. This is a graduate-level course that is of interest to electrical and computer engineering, biomedical engineering, computer science, and neuroscience students.

### **Prerequisites**:

EE503, or equivalent, or permission of the instructor. Students should be familiar with basic probability concepts. EE503 will be **waived** for any such students. Please contact the instructor if you are unsure of the prerequisite.

### **Course Website:**

The course material and problem sets will be posted on Blackboard: https://blackboard.usc.edu

### **Readings:**

There are no required textbooks. Lecture slides/notes will be posted on the Blackboard website for many parts of the course. There will be various papers used as helpful reference reading material (examples listed below) and can be accessed through the libraries.

## Course Grade:

This is an advanced graduate class. The course grade will be on the basis of a class project, a project proposal combined with a project pitch presentation in the 6<sup>th</sup> week of the course, a 15min final project presentation, a final project report, and homework assignments. The project and presentation should involve developing and implementing a data analysis technique and testing it on real and/or simulated data. The topic should be submitted for approval by the end of the 6<sup>th</sup> week of class in the form of a project proposal and project pitch presentation. In lieu of a final exam, the final report will be due at the time normally reserved for this class's final exam.

	Topics/Daily Activities	Readings
Week 1	Course overview and review of probability concepts	[1-5]
Week 2	Linear dynamical systems	[1-5]
	State-space models	
Week 3	Recursive Bayesian estimation	[1-5]
	Kalman filtering and smoothing	
Week 4	Point process theory	[6-11]
	Generalized linear models	
	Spike train analysis	
Week 5	Machine learning methods for spiking models: maximum-	[6-11]
	likelihood, time-rescaling theorem, goodness of fit,	
	simulating a point process	
Week 6	Recursive Bayesian estimation for spike trains: point	[5,6,12,13]
	process filtering, point process smoothing	
		Project proposal due
		Project pitch presentations
		will be held in the 6 <sup>th</sup> week
Week 7	Measures of functional connectivity, Granger causality,	[14-19]
	directed information	
Week 8	Unsupervised learning and application to neural data	[12,20-24]
	analysis: expectation-maximization (EM)	
	subspace identification	
Week 9	Application to hippocampal neural activity	[12, 13, 25]

## Tentative Course Schedule: A Weekly Breakdown

	Application to open-loop neural decoding	
Week	Dynamic programming and optimal control	[26,27]
10	Linear quadratic regulator (LQR), linear Gaussian regulator	
	(LQG)	
Week	Closed-loop neurotechnologies for control of movement	[28-42]
11		
Week	Closed-loop neurotechnologies for control of anesthesia	[43-46]
12		
Week	Closed-loop neurotechnologies for electrical brain	[47-53]
13	stimulation	
Week	Multiscale and multimodal data fusion, modeling, and	[54-57]
14	decoding	
Week	Student final presentations	
15		
FINAL	Final report is due at the time the University would	
Date	otherwise designate for a final exam for this class	

### REFERENCES

The following list contains the list of example books and papers that will be used as helpful reference reading material and can be accessed through the libraries. Each semester, the list of papers will be updated with new papers added to the list. The books will not be required for purchase.

[1] T. Kailath, A. Sayed, and B. Hassibi, Linear estimation. Prentice Hall NJ: 2000, vol. 1.

[2] J. M. Mendel, Lessons in estimation theory for signal processing, communications, and control. Prentice Hall NJ: 1995.

[3] S. M. Kay, Fundamentals of statistical signal processing: estimation theory. Prentice Hall NJ: 1993.

[4] H. E. Rauch, C. Striebel, and F. Tung, "Maximum likelihood estimates of linear dynamic systems," AIAA journal, vol. 3, no. 8, pp. 1445–1450, 1965.

[5] M. M. Shanechi, "Brain-machine interface control algorithms", IEEE Transactions on Neural Systems and Rehabilitation Engineering, vol. 25, no. 10, pp. 1725–1734, 2017.

[6] W. Truccolo, U. Eden, M. Fellows, J. Donoghue, and E. Brown, "A point process framework for relating neural spiking activity to spiking history, neural ensemble, and extrinsic covariate effects," Journal of Neurophysiology, vol. 93, no. 2, pp. 1074–1089, 2005.

[7] E. N. Brown, "Theory of point processes for neural systems," Les Houches, vol. 80, pp. 691–727, 2005.

[8] D. Daley and D. Vere-Jones, An introduction to the theory of point processes: volume II: general theory and structure. Springer, 2007, vol. 2.

[9] E. Brown, R. Barbieri, V. Ventura, R. Kass, and L. Frank, "The time-rescaling theorem and its application to neural spike train data analysis," Neural Computation, vol. 14, no. 2, pp. 325–346, 2002.

[10] R. E. Kass and V. Ventura, "A spike-train probability model," Neural Computation, vol. 13, no. 8, pp. 1713–1720, 2001.

[11] L. Paninski, J. Pillow, and J. Lewi, "Statistical models for neural encoding, decoding, and optimal stimulus design," Progress in Brain Research, vol. 165, pp. 493–507, 2007.

[12] A. Smith and E. Brown, "Estimating a state-space model from point process observations," Neural Computation, vol. 15, no. 5, pp. 965–991, 2003.

[13] U. Eden, L. Frank, R. Barbieri, V. Solo, and E. Brown, "Dynamic analysis of neural encoding by point process adaptive filtering," Neural Computation, vol. 16, no. 5, pp. 971–998, 2004.

[14] C. J. Quinn, T. P. Coleman, N. Kiyavash, N. G. Hatsopoulos, "Estimating the directed information to infer causal relationships in ensemble neural spike train recordings," Journal of Computational Neuroscience, vol. 30, no. 1, pp. 17–44, 2011.

[15] C. J. Quinn, N. Kiyavash, T. P. Coleman, "Directed information graphs," IEEE Transactions on information theory, vol. 61, no. 12, pp. 6887–6909, 2015.

[16] M. Kaminski, M. Ding, W. Truccolo, and S. Bressler, "Evaluating causal relations in neural systems: Granger causality, directed transfer function and statistical assessment of significance," Biological Cybernetics, vol. 85, no. 2, pp. 145–157, 2001.

[17] S. Kim, D. Putrino, S. Ghosh, and E. Brown, "A Granger causality measure for point process models of ensemble neural spiking activity," PLoS Computational Biology, vol. 7, no. 3, p. e1001110, 2011.

[18] M. Okatan, M. Wilson, and E. Brown, "Analyzing functional connectivity using a network likelihood model of ensemble neural spiking activity," Neural Computation, vol. 17, no. 9, pp. 1927–1961, 2005.

[19] C. Wang, M. M. Shanechi M. M., "Estimating multiscale direct causality graphs in neural spike-field networks", IEEE Transactions on Neural Systems and Rehabilitation Engineering, vol. 27, no. 5, pp. 857–866, 2019.

[20] A. P. Dempster, N. M. Laird, and D. B. Rubin, "Maximum likelihood from incomplete data via the EM algorithm," Journal of the Royal Statistical Society. Series B (Methodological), pp. 1–38, 1977.

[21] J. A. Bilmes et al., "A gentle tutorial of the EM algorithm and its application to parameter estimation for gaussian mixture and hidden Markov models," International Computer Science Institute, vol. 4, no. 510, p. 126, 1998.

[22] Z. Ghahramani, G. E. Hinton, "Parameter estimation for linear dynamical systems," Dept. Comput. Sci., Univ. Toronto, Toronto, ON, Canada, Tech. Rep. CRG-TR-96-2, 1996.

[23] L. Ljung, System Identification, Prentice Hall, NJ: 1999.

[24] P. Van Overschee, B. L. De Moor, "Subspace identification for linear systems: Theory–Implementation–Applications", Springer, 2012.

[25] R. Barbieri, L. Frank, D. Nguyen, M. Quirk, V. Solo, M. Wilson, and E. Brown, "Dynamic analyses of information encoding in neural ensembles," Neural Computation, vol. 16, no. 2, pp. 277–307, 2004.

[26] D. Bertsekas, Dynamic programming and optimal control. Athena Scientific, 2005.

[27] R. F. Stengel, Optimal control and estimation. Dover publications, 1994.

[28] S.-P. Kim, J. D. Simeral, L. R. Hochberg, J. P. Donoghue, and M. J. Black, "Neural control of computer cursor velocity by decoding motor cortical spiking activity in humans with tetraplegia," Journal of Neural Engineering, vol. 5, pp. 455–476, 2008.

[29] C. T. Moritz, S. I. Perlmutter, and E. E. Fetz, "Direct control of paralysed muscles by cortical neurons," Nature, vol. 456, pp. 639–643, 2008.

[30] K. Ganguly, J. M. Carmena, "Emergence of a stable cortical map for neuroprosthetic control", PLoS biology, vol. 7, no. 7, 2009.

[31] A. J. Suminski, D. C. Tkach, A. H. Fagg, and N. G. Hatsopoulos, "Incorporating feedback from multiple sensory modalities enhances brain-machine interface control," Journal of Neuroscience, vol. 30, no. 50, pp.16777–16787, 2010.

[32] J. E. O'Doherty, M. A. Lebedev, P. J. Ifft, K. Z. Zhuang, S. Shokur, H. Bleuler, and M. A. L. Nicolelis, "Active tactile exploration using a brain-machine-brain interface," Nature, vol. 479, pp. 228–231, 2011.

[33] A. L. Orsborn, S. Dangi, H. G. Moorman, and J. M. Carmena, "Closed-loop decoder adaptation on intermediate time-scales facilitates rapid BMI performance improvements independent of decoder initialization conditions," IEEE Transactions on Neural Systems and Rehabilitation Engineering, vol. 20, no. 4, pp. 468–477, 2012.

[34] V. Gilja, P. Nuyujukian, C. A. Chestek, J. P. Cunningham, B. M. Yu, J. M. Fan, M. M. Churchland, M. T. Kaufman, J. C. Kao, S. I. Ryu, and K. V. Shenoy, "A high-performance neural prosthesis enabled by control algorithm design," Nature Neuroscience, vol. 15, pp. 1752–1757, 2012.

[35] M. M. Shanechi, R. C. Hu, M. Powers, G. W. Wornell, E. N. Brown, and Z. M. Williams, "Neural population partitioning and a concurrent brain-machine interface for sequential motor function," Nature Neuroscience, vol. 15, no. 12, pp. 1715–1722, 2012.

[36] C. Ethier, E. R. Oby, M. J. Bauman, and L. E. Miller, "Restoration of grasp following paralysis through brain-controlled stimulation of muscles," Nature, vol. 485, pp. 368–371, 2012.

[37] L. R. Hochberg, D. Bacher, B. Jarosiewicz, N. Y. Masse, J. D. Simeral, J. Vogel, S. Haddadin, J. Liu, S. S. Cash, P. van der Smagt, and J. P. Donoghue, "Reach and grasp by people with tetraplegia using a neurally controlled robotic arm," Nature, vol. 485, pp. 372–375, 2012.

[38] J. L. Collinger, B. Wodlinger, J. E. Downey, W. Wang, E. C. Tyler-Kabara, D. J. Weber, A. J. McMorland, M. Velliste, M. L. Boninger, and A. B. Schwartz, "High-performance neuroprosthetic control by an individual with tetraplegia," The Lancet, vol. 381, no. 9866, pp. 557–564, 2013.

[39] M. M. Shanechi, Z. M. Williams, G. W. Wornell, R. Hu, M. Powers, and E. N. Brown, "A real-time brain-machine interface combining motor target and trajectory intent using an optimal feedback control design," PLOS ONE, vol. 8, no. 4, p. e59049, 2013.

[40] T. Aflalo, S. Kellis, C. Klaes, B. Lee, Y. Shi, K. Pejsa, K. Shanfield, S. Hayes-Jackson, M. Aisen, C. Heck, C. Liu, and R. A. Andersen, "Decoding motor imagery from the posterior parietal cortex of a tetraplegic human" Science, vol. 348, no. 6237, pp. 906–910, 2015.

[41] M. M. Shanechi M. M., A. L. Orsborn, J. M. Carmena, "Robust brain-machine interface design using optimal feedback control modeling and adaptive point process filtering", PLoS Computational Biology, 12 (4):e1004730, 2016.

[42] M. M. Shanechi, A. L. Orsborn, H. Moorman, S. Gowda, S. Dangi, J. M. Carmena J. M, "Rapid control and feedback rates enhance neuroprosthetic control", Nature Communications, 8:13825, 2017.

[43] P. L. Purdon et al, "Electroencephalogram signatures of loss and recovery of consciousness from propofol", Proc. Natl Acad. Sci., vol. 110, no. 12, p. E1142–51, 2013.

[44] M. M. Shanechi, J. J. Chemali, M. Liberman, K. Solt, and E. N. Brown, "A brain-machine interface for control of medically-induced coma," PLoS Computational Biology, vol. 9, no. 10, p. e1003284, 2013.

[45] S. Ching, M. Liberman, J. Chemali, M.B. Westover, K. Solt, P.L. Purdon, and E.N. Brown, "Real-time closed loop control in a rodent model of medically-induced coma", Anesthesiology, vol. 119, no. 4, p. 848-860, 2013.

[46] Y. Yang and M. M. Shanechi, "An adaptive and generalizable closed-loop system for control of medically-induced coma and other states of anesthesia," Journal of Neural Engineering, vol. 13, p. 066019, 2016.

[47] K. B. Hoang, I. R. Cassar, W. M. Grill, D. A. Turner, "Biomarkers and Stimulation Algorithms for Adaptive Brain Stimulation", Frontiers in Neuroscience, vol. 11, pp. 564, 2017

[48] M. M. Shanechi, "Brain-machine interfaces from motor to mood", Nature Neuroscience, vol. 22, no. 10, pp. 1554-1564, 2019

[49] S. Santaniello, G. Fiengo, L. Glielmo, W. M. Grill, "Closed-loop control of deep brain stimulation: a simulation study," IEEE Transactions on Neural Systems and Rehabilitation Engineering, vol. 19, pp. 15–24, 2011.

[50] Yang Y., Connolly A. T., Shanechi M. M., "A control-theoretic system identification framework and a real-time closed-loop clinical simulation testbed for electrical brain stimulation. Journal of Neural Engineering vol. 15, no. 6, pp. 066007, 2018

[51] Sani O. G., Yang Y., Lee M. B., Dawes H. E., Chang E.F., Shanechi M. M., "Mood variations decoded from multi-site intracranial human brain activity", Nature Biotechnology, vol. 36, no. 10, pp. 954-961, 2018

[52] M. F. Bolus, A. A. Willats, C. J. Whitmire, C. J. Rozell, G. B. Stanley, "Design Strategies for Dynamic Closed-Loop Optogenetic Neurocontrol *in vivo*", Journal of Neural Engineering vol. 15, no. 2, pp. 026011, 2018

[53] D. C. Millard, Q. Wang, C. A. Gollnick, G. B. Stanley "System identification of the nonlinear dynamics in the thalamocortical circuit in response to patterned thalamic microstimulation in vivo", Journal of Neural Engineering, vol. 10, no. 6, pp. 066011, 2013

[54] A. K. Bansal, W. Truccolo, C. E. Vargas-Irwin, J. P. Donoghue "Decoding 3D reach and grasp from hybrid signals in motor and premotor cortices: spikes, multiunit activity, and local field potentials." Journal of Neurophysiology, vol. 107, pp. 1337–1355, 2012.

[55] S. D. Stavisky, J. C. Kao, P. Nuyujukian, S. I. Ryu, K. V. Shenoy "A high performing brain-machine interface driven by low-frequency local field potentials alone and together with spikes." Journal of Neural Engineering, vol. 12, p. 036009, 2015

[56] H. Hsieh, Y. Wong, B. Pesaran, M. M. Shanechi, "Multiscale Modeling and Decoding Algorithms for Spike-Field Activity", Journal of Neural Engineering, vol. 16, no. 1, pp. 016018, 2018

[57] Abbaspourazad H., Hsieh H., Shanechi M. M., "A multiscale dynamical modeling and identification framework for spike-field activity", IEEE Transactions on Neural Systems and Rehabilitation Engineering, vol. 27, no. 6, pp. 1128–1138, 2019

### Statement on Academic Conduct and Support Systems

### Academic Conduct

Plagiarism – presenting someone else's ideas as your own, either verbatim or recast in your own words – is a serious academic offense with serious consequences. Please familiarize yourself with the discussion of plagiarism in *SCampus* in Section 11, *Behavior Violating University Standards* <u>https://scampus.usc.edu/1100-behavior-violating-university-standards-and-appropriate-sanctions</u>. Other forms of academic dishonesty are equally unacceptable. See additional information

in *SCampus* and university policies on scientific misconduct, <u>http://policy.usc.edu/scientific-misconduct</u>.

Discrimination, sexual assault, and harassment are not tolerated by the university. You are encouraged to report any incidents to the *Office of Equity and Diversity* <u>http://equity.usc.edu</u> or to the *Department of Public Safety* <u>http://adminopsnet.usc.edu/department/department-public-safety</u>. This is important for the safety of the whole USC community. Another member of the university community – such as a friend, classmate, advisor, or faculty member – can help initiate the report, or can initiate the report on behalf of another person. *The Center for Women and Men* http://www.usc.edu/student-affairs/cwm/ provides 24/7 confidential support, and the sexual assault resource center webpage <u>http://sarc.usc.edu</u> describes reporting options and other resources.

### Support Systems

A number of USC's schools provide support for students who need help with scholarly writing. Check with your advisor or program staff to find out more. Students whose primary language is not English should check with the *American Language Institute* <u>http://dornsife.usc.edu/ali</u>, which sponsors courses and workshops specifically for international graduate students. *The Office of Disability Services and Programs* <u>http://sait.usc.edu/academicsupport/centerprograms/dsp/home\_index.html</u> provides certification for students with disabilities and helps arrange the relevant accommodations. If an officially declared emergency makes travel to campus infeasible, *USC Emergency Information* <u>http://emergency.usc.edu</u> will provide safety and other updates, including ways in which instruction will be continued by means of blackboard, teleconferencing, and other technology.